

1. A random process $x(n)$ has correlation matrix

$$\mathbf{R} = \begin{bmatrix} 4 & 1 & 0 & 0 \\ 1 & 4 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

- (a) Determine the KLT basis functions.
 (b) Determine the minimum mean square error achievable when using a single term approximation, e.g.,

$$\hat{x}(n) = c_1(n)\mathbf{q}_1$$

- (c) Determine the error when 2, 3 and 4 terms are used.

Solution.

(a) Eigenvalues of \mathbf{R} :

$$\lambda_1 = 1, \lambda_2 = \lambda_3 = 3, \lambda_4 = 5.$$

The corresponding eigenvectors:

$$\begin{aligned} \mathbf{q}_1 &= [0, 0, -\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}]^T \\ \mathbf{q}_2 &= [-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0, 0]^T \\ \mathbf{q}_3 &= [0, 0, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}]^T \\ \mathbf{q}_4 &= [\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0, 0]^T \end{aligned}$$

Hence, $\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3, \mathbf{q}_4$ are the KLT basis functions.

(b)

$$\begin{aligned} \hat{x}(n) &= c_1(n)\mathbf{q}_1 \\ \varepsilon(n) &= x(n) - \hat{x}(n) \end{aligned}$$

When single item is used, the MSE is given by

$$\begin{aligned} \varepsilon_{MSE} &= E[\varepsilon(n)^H \varepsilon(n)] \\ &= \sum_{i=1}^4 \lambda_i - \lambda_{j,j=1,2,3,4} \end{aligned}$$

Choose the biggest eigenvalue, the minimum available MSE is 7.

(c) When 2 items are used, the minimum available MSE is 4. When 3 items are used, the minimum available MSE is 1. When 4 items are used, the minimum available MSE is 0.

2. A real random process is defined by

$$x(n) = A \cos \omega_0 n + w(n)$$

where A is a Gaussian random variable with mean zero and variance σ_A^2 and $w(n)$ is a white noise process independent of A with variance σ_w^2 .

- (a) What is the correlation function of $x(n)$?
- (b) Can the power spectral density of $x(n)$ be defined? If so, what is the power spectral density function?
- (c) Repeat (a) and (b) in the case when the cosine has an independent random phase uniformly distributed on $[-\pi, \pi]$.

Solution.

(a) The correlation function $r_x(n, n - k)$

$$\begin{aligned} r_x(n, n - k) &= E\{x(n)x^*(n - k)\} \\ &= \sigma_A^2 \cos(\omega_0 n) \cos(\omega_0(n - k)) + \sigma_w^2 \delta(k) \\ &= \frac{\sigma_A^2}{2} [\cos(\omega_0 k) + \cos(\omega_0(2n - k))] + \sigma_w^2 \delta(k) \end{aligned}$$

(b) Since the correlation function $r_x(n, n - k)$ is not independent with n , the process is not wide-sense stationary. Therefore, the power spectral density function can not be defined.

(c) If

$$x(n) = A \cos(\omega_0 n + \theta), \quad \theta \in \{-\pi, \pi\}$$

Then,

$$\begin{aligned} r_x(n, n - k) &= E\{x(n)x^*(n - k)\} \\ &= \frac{\sigma_A^2}{2} \cos(\omega_0 k) + \sigma_w^2 \delta(k) + \frac{\sigma_A^2}{2} \underbrace{E[\cos(\omega_0(2n - k) + 2\theta)]}_0 \\ &= \frac{\sigma_A^2}{2} \cos(\omega_0 k) + \sigma_w^2 \delta(k) \end{aligned}$$

Since the correlation function $r_x(n, n - k)$ only depends on k , this process is wide-sense stationary. Therefore, we can define the power spectral density function of $x(n)$.

$$S_x(\omega) = \frac{\sigma_A^2}{4} [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)] + \sigma_w^2$$

3. A linear system is defined by

$$y(n) = 0.7y(n - 1) + x(n) - x(n - 1)$$

- (a) Compute the first four values of $R_{yx}(l)$ it is known that $R_x(l) = \delta(l)$.

- (b) What is $R_{yx}(l)$ for $-3 \leq l \leq 3$?
 (c) What is the power spectral density function $S_y(\omega)$?

Solution.

(a)

$$\begin{aligned} y(n) &= 0.7y(n-1) + x(n) - x(n-1) \\ Y(z) &= 0.7z^{-1}Y(z) + X(z) - z^{-1}X(z) \\ H(z) &= \frac{Y(z)}{X(z)} = \frac{1 - z^{-1}}{1 - 0.7z^{-1}} \\ h(n) &= 0.7^n u(n) - 0.7^{n-1} u(n-1) \end{aligned}$$

Since

$$\begin{aligned} R_{yx}(l) &= h(l) * R_x(l) \\ &= h(l) * \delta(l) \\ &= h(l) \end{aligned}$$

Therefore, the first four values of $R_{yx}(l)$ are $\{1, -0.3, -0.21, -0.147\}$.

(b) $R_{yx}(l) = \{0, 0, 0, 1, -0.3, -0.21, -0.147\}, -3 \leq l \leq 3.$

(c)

$$\begin{aligned} R_y(l) &= h(l) * h^*(-l) * R_x(l) \\ &= h(l) * h^*(-l) \end{aligned}$$

Then,

$$\begin{aligned} S_y(\omega) &= |H(\omega)|^2 \\ &= \left| \frac{1 - e^{-j\omega}}{1 - 0.7e^{-j\omega}} \right|^2 \\ &= \frac{2 - 2 \cos(\omega)}{1.49 - 1.4 \cos(\omega)} \end{aligned}$$

4. A random process is defined by

$$x(n) = s(n) + \eta(n)$$

where $\eta(n)$ is a unit variance white noise process and $s(n)$ is defined by

$$s(n) = \rho s(n-1) + w(n)$$

where $w(n)$ is another unit variance white noise process independent of $\eta(n)$.

- (a) Determine the correlation function $R_x(l)$.
 (b) Determine the power spectral density function $S_x(\omega)$.

Solution.

(a)

$$\begin{aligned} R_x(l) &= E\{x(n)x^*(n-l)\} \\ &= E\{[s(n) + \eta(n)][s(n-l) + \eta(n-l)]^*\} \\ &= R_s(l) + R_\eta(l) \end{aligned}$$

and

$$\begin{aligned} R_s(l) &= E\{s(n)s^*(n-l)\} \\ &= E\{[\rho s(n-1) + w(n)]s^*(n-l)\} \\ &= \rho R_s(l-1) \end{aligned}$$

Since

$$\begin{aligned} R_s(0) &= E\{[\rho s(n-1) + w(n)][\rho s(n-1) + w(n)]^{ast}\} \\ &= \rho^2 R_s(0) + 1 \end{aligned}$$

,

$$R_s(0) = \frac{1}{1 - \rho^2}$$

Therefore

$$R_s(l) = \frac{\rho^{|l|}}{1 - \rho^2}$$

Then

$$R_x(l) = \frac{\rho^{|l|}}{1 - \rho^2} + \delta(l)$$

(b)

$$S_x(\omega) = 1 + \frac{1}{1 + \rho^2 - 2\rho \cos(\omega)}$$

5. Recall the system

$$y(n) = \mathbf{w}^T \mathbf{x}(n)$$

where $\mathbf{x}(n) = \mathbf{u}(n) + \mathbf{v}(n)$. It was proven in class that the matched filter for a deterministic signal, corrupted by white noise, is given

$$\mathbf{w} = k\mathbf{u}^*(n)$$

where \mathbf{w} is the vector of filter coefficients and $\mathbf{u}(n)$ is the deterministic signal. Suppose now the noise is colored (i.e. $\mathbf{R}_v \neq \sigma_v^2 \mathbf{I}$). Utilize the transformation

$$\mathbf{x}'(n) = k\mathbf{R}_v^{-1/2} \mathbf{x}(n)$$

to determine a similar result for the colored noise case.

Solution.

$$\begin{aligned}
 \text{SNR} &= \frac{|y_s(n)|^2}{E\{|y_n(n)|^2\}} \\
 &= \frac{\mathbf{w}^H \mathbf{u}^*(n) \mathbf{u}^T(n) \mathbf{w}}{E\{\mathbf{w}^H \mathbf{v}^*(n) \mathbf{v}^T(n) \mathbf{w}\}} \\
 &= \frac{|\mathbf{w}^H \mathbf{u}^*(n)|^2}{\mathbf{w}^H \mathbf{R}_v \mathbf{w}}
 \end{aligned}$$

Since \mathbf{R}_v is Hermitian and positive definite, $\mathbf{R}_v = \mathbf{L} \cdot \mathbf{L}^H$.

$$\begin{aligned}
 \text{SNR} &= \frac{|\mathbf{w}^H \mathbf{L} \mathbf{L}^{-1} \mathbf{u}^*(n)|^2}{\mathbf{w}^H \mathbf{L} \mathbf{L}^H \mathbf{w}} \\
 &= \frac{|(\mathbf{L}^H \mathbf{w})^H \cdot (\mathbf{L}^{-1} \mathbf{u}^*(n))|^2}{\underbrace{(\mathbf{L}^H \mathbf{w})^H \mathbf{L}^H \mathbf{w}}_{\text{Cauchy-Schwarz inequality}}} \\
 &\leq \frac{|\mathbf{L}^H \mathbf{w}|^2 \cdot |\mathbf{L}^{-1} \mathbf{u}^*(n)|^2}{|\mathbf{L}^H \mathbf{w}|^2} \\
 &= |\mathbf{L}^{-1} \mathbf{u}^*(n)|^2
 \end{aligned}$$

The maximum SNR is achieved when

$$\begin{aligned}
 \mathbf{L}^H \mathbf{w} &= k \mathbf{L}^{-1} \mathbf{u}^*(n) \\
 \mathbf{w} &= k \mathbf{R}_v^{-1} \mathbf{u}^*(n)
 \end{aligned}$$

6. (a) Determine the mean of the exponential density function $f_x(x) = \alpha e^{-\alpha x} U(x)$, and expressed the density in terms of the mean parameter $\mu = E\{x\}$.
- (b) Given independence samples x_1, x_2, \dots, x_N , determine the ML estimate of μ .
- (c) Is the estimate unbiased?
- (d) Is it consistent?
- (e) What is the variance of the estimate? Is it a minimum variance estimate?

Solution.

(a)

$$\mu = E[x] = \int_0^{\infty} \alpha e^{-\alpha x} dx = \frac{1}{\alpha}$$

(b)

$$\begin{aligned}
 f_{x_1, x_2, \dots, x_N}(x_1, x_2, \dots, x_N) &= \prod_{i=1}^N f_{x_i}(x_i) \\
 &= \alpha^N e^{-\alpha \sum_{i=1}^N x_i}
 \end{aligned}$$

$$\frac{df_{x_1, x_2, \dots, x_N}(x_1, x_2, \dots, x_N)}{d\alpha} = N\alpha^{N-1}e^{-\sum_{i=1}^N \alpha} + \alpha^N \left(-\sum_{i=1}^N x_i\right) e^{-\sum_{i=1}^N \alpha} = 0$$

↓

$$\alpha = \frac{N}{\sum_{i=1}^N x_i}$$

So, the maximum likelihood estimate of μ is

$$\hat{\mu} = \frac{\sum_{i=1}^N x_i}{N}$$

(c)

$$\begin{aligned} E[\hat{\mu}] &= E\left[\frac{\sum_{i=1}^N x_i}{N}\right] \\ &= \frac{\sum_{i=1}^N E[x_i]}{N} \\ &= \frac{\sum_{i=1}^N \mu}{N} \\ &= \mu \end{aligned}$$

So, the estimate is unbiased.

(d)

$$\begin{aligned} E[\hat{\mu}_N^2] &= E\left[\left(\frac{1}{N}\sum_{i=1}^N x_i\right)\left(\frac{1}{N}\sum_{j=1}^N x_j\right)\right] \\ &= \frac{1}{N^2}\left(\sum_{i=1}^N E[x_i^2] + \sum_{i \neq j} E[x_i]E[x_j]\right) \\ &= \frac{1}{N^2}\left(\sum_{i=1}^N \frac{2}{\alpha^2} + N(N-1)\frac{1}{\alpha^2}\right) \\ &= \frac{1}{\alpha^2}\left(1 + \frac{1}{N}\right) \end{aligned}$$

The variance of the estimate is

$$\begin{aligned} \text{var}(\hat{\mu}_N) &= E[\hat{\mu}^2] - E[\hat{\mu}]^2 \\ &= \frac{1}{\alpha^2}\left(1 + \frac{1}{N}\right) - \frac{1}{\alpha^2} \\ &= \frac{1}{N\alpha^2} \\ &= \frac{\mu^2}{N} \end{aligned}$$

$$\text{var}(\hat{\mu}_N) < \text{var}(\hat{\mu}_{N-1})$$

Also, from (3), $\hat{\mu}_N$ is unbiased.

So, $\hat{\mu}_N$ is a consistent estimate.

(e)

$$f_{\mathbf{x}|\mu}(\mathbf{x}|\mu) = \frac{1}{\mu^N} e^{-\frac{\sum_{i=1}^N x_i}{\mu}}$$

$$\ln[f_{\mathbf{x}|\mu}(\mathbf{x}|\mu)] = -N \ln \mu - \frac{\sum_{i=1}^N x_i}{\mu}$$

$$\frac{\partial^2}{\partial \mu^2} \ln[f_{\mathbf{x}|\mu}(\mathbf{x}|\mu)] = \frac{N}{\mu^2} - \frac{2 \sum_{i=1}^N x_i}{\mu^3}$$

$$E \left[\frac{\partial^2}{\partial \mu^2} \ln[f_{\mathbf{x}|\mu}(\mathbf{x}|\mu)] \right] = -\frac{N}{\mu^2}$$

$$\left(-E \left[\frac{\partial^2}{\partial \mu^2} \ln[f_{\mathbf{x}|\mu}(\mathbf{x}|\mu)] \right] \right)^{-1} = \frac{\mu^2}{N} = \text{var}(\hat{\mu}_N)$$

That is, the estimate $\hat{\mu}_N = \frac{\sum_{i=1}^N x_i}{N}$ hits the Cramer-Rao Bound.

So, the unbiased estimate $\hat{\mu}_N$ is a minimum variance estimate.

7. The joint density function of random variables x and y is given by

$$f_{xy}(x, y) \begin{cases} 8xy & 0 \leq y \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

- Determine and sketch the conditional density function $f_{y|x}(y|x)$.
- Determine the MAP estimate of y .
- Determine the MS estimate of y .
- Determine the MAE estimate of y .

Solution.

(a)

$$f(x) = \int_0^x 8xy dy = 4x^3 \quad 0 \leq x \leq 1$$

$$f_{y|x}(y|x) = \frac{f_{x,y}(x,y)}{f(x)} = \frac{2y}{x^2} \quad 0 \leq y \leq x$$

(b) $\hat{y}_{\text{MAP}} = x$

(c)

$$\begin{aligned} \hat{y}_{\text{MS}} &= E\{y|x\} \\ &= \int_0^x y \frac{2y}{x^2} dy \\ &= \frac{2x}{3} \end{aligned}$$

(d)

$$F_{y|x}(y|x) = \begin{cases} 0 & y < 0 \\ \frac{y^2}{x^2} & 0 \leq y \leq x \\ 1 & y > x \end{cases}$$

Therefore, $\hat{y}_{\text{MAE}} = \frac{x}{\sqrt{2}}$.

8. A two-dimensional vector \mathbf{x} and a random variable y have the joint density

$$f_{\mathbf{x}y}(\mathbf{x}, y) \begin{cases} A(y + 6x_1)x_2 & 0 \leq x_1, x_2, y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Assume that \mathbf{x} represents the observation.

- (a) Determine the MAP estimate of y .
- (b) Determine the MS estimate of y .
- (c) Determine the MAE estimate of y .

Solution.

(a)

$$f_{\mathbf{x}}(\mathbf{x}) = \int f_{\mathbf{x},y}(\mathbf{x}, y) dy = A\left(\frac{1}{2} + 6x_1\right)x_2, \quad 0 \leq x_1, x_2 \leq 1$$

$$f_{y|\mathbf{x}}(y|\mathbf{x}) = \frac{f_{\mathbf{x},y}(\mathbf{x}, y)}{f_{\mathbf{x}}(\mathbf{x})} = \frac{y + 6x_1}{1/2 + 6x_2}, \quad 0 \leq x_1, y \leq 1$$

$$\hat{y}_{\text{MAP}} = \arg \max_y f_{y|\mathbf{x}}(y|\mathbf{x}) = 1$$

(b)

$$\hat{y}_{\text{MS}} = E\{y|\mathbf{x}\} = \int_0^1 y \frac{y + 6x_1}{1/2 + 6x_2} dy = \frac{2 + 18x_1}{3 + 36x_2}$$

(c)

$$F_{y|\mathbf{x}}(y|\mathbf{x}) = \int_0^{\hat{y}_{\text{MAE}}} \frac{y + 6x_1}{1/2 + 6x_2} dy = \frac{1}{2}$$

Therefore, $\hat{y}_{\text{MAE}} = -6x_1 + \sqrt{36x_1^2 + 6x_2 + 1/2}$.

9. A random process $x[n]$ is generated according to the difference equation

$$x[n] = \rho x[n-1] + \eta[n]$$

where ρ is a constant and is a binary whitenoise sequence taking on values -1 and $+1$ with equal probabilities.

- Generate and plot $M = 50$ samples of the random sequence for $\rho = 0.95, 0.70$, and -0.95 . What differences do you observe in these three random sequences?
- Repeat the above with $\eta[n]$ a white noise Gaussian sequence with unit variance.
- Let $\hat{R}_x[l]$ be the sample autocorrelation. Define the estimated correlation coefficient $\hat{\rho}$ as

$$\hat{\rho} = \frac{\hat{R}_x[1]}{\hat{R}_x[0]}$$

Compute $\hat{\rho}$ for each of the Gaussian noise driven sequences and for several sequence lengths. How well does the estimated value compare with the theoretical value?

- Plot the estimated $\hat{R}_x[l]$ and true $R_x[l]$ autocorrelation functions for $0 \leq l \leq 1$ for each of the Gaussian noise driven sequences.
- What happens if $|\rho| > 1$?