

1. Let

$$\mathbf{R} = \begin{bmatrix} 2 & -2 \\ -2 & 5 \end{bmatrix}$$

Express  $\mathbf{R}$  as  $\mathbf{R} = \mathbf{Q}\mathbf{\Omega}\mathbf{Q}^H$ , where  $\mathbf{\Omega}$  is diagonal.

2. The two-dimensional covariance matrix can be expressed as:

$$\mathbf{C} = \begin{bmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho^*\sigma_1\sigma_2 & \sigma_2^2 \end{bmatrix}$$

- Find the simplest expression for the eigenvalues of  $\mathbf{C}$ .
- Specialize the results to the case  $\sigma_1^2 = \sigma_2^2 = \sigma^2$ .
- What are the eigenvectors in the special case (b) when  $\rho$  is real?

3. Let

$$x[n] = Ae^{j\omega_0 n}$$

where the complex amplitude  $A$  is a RV with random magnitude and phase

$$A = |A|e^{j\phi}.$$

Show that a sufficient condition for the random process to be stationary is that the amplitude and phase are independent and that the phase is uniformly distributed over  $[-\pi, \pi]$ .

4. Let  $X_i$  be i.i.d. RVs uniformly distributed on  $[0, 1]$  and define

$$Y = \sum_{i=1}^{20} X_i.$$

Utilize Tchebycheff's inequality to determine a bound for  $Pr\{8 < Y < 12\}$ .

5. Let  $X \sim \mathcal{N}(0, 2\sigma^2)$  and  $Y \sim \mathcal{N}(0, \sigma^2)$  be independent RVs. Also, define  $Z = XY$ . Find the Bays estimate of  $X$  from observation  $Z$ :

- Using the squared error criteria.
- Using the absolute error criteria.

6. Let  $X$  and  $Y$  be independent RVs characterized by  $f_X(x) = ae^{-ax}U(x)$  and  $f_Y(y) = ae^{-ay}U(y)$ . Also, define  $Z = XY$ . Find the Bays estimate of  $X$  from observation  $Z$  using the uniform cost function.

7. Random processes  $x[n]$  and  $y[n]$  are defined by

$$\begin{aligned} x[n] &= v_1[n] + 3v_2[n-1] \\ y[n] &= v_2[n+1] + 3v_2[n-1] \end{aligned}$$

where  $v_1[n]$  and  $v_2[n]$  are independent white noise processes, each with variance 0.5.

- Determine the autocorrelation functions of  $x$  and  $y$ . Are the processes WSS?

(b) Determine the cross-correlation functions between  $x$  and  $y$ . Are the processes jointly WSS?

8. A random process  $x(n)$  has correlation matrix

$$\mathbf{R} = \begin{bmatrix} 4 & 1 & 0 & 0 \\ 1 & 4 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

(a) Determine the KLT basis functions.

(b) Determine the minimum mean square error achievable when using a single term approximation, e.g.,

$$\hat{x}(n) = c_1(n)\mathbf{q}_1$$

(c) Determine the error when 2, 3 and 4 terms are used.

9. Let

$$v[n] = a_1^*x[n] + a_2^*y[n]$$

where  $x$  and  $y$  are WSS processes. Show that the coherence satisfies

$$|\Gamma(\omega)|^2 = \frac{|S_{xy}(\omega)|^2}{S_x(\omega)S_y(\omega)} \geq 1$$

where  $S_x(\omega), S_y(\omega), S_{xy}(\omega)$  are PSD and cross-PSD functions. HINT: Write the output PSD function using a matrix expression,  $S_v(\omega) = \mathbf{a}^H \mathbf{S} \mathbf{a}$ , and use known properties.

10. Let  $\{x[n]\}$  be a process of i.i.d. RVs uniform on  $[-1, 1]$ . The process is passed through a LTI system with impulse response  $h[n] = (\frac{1}{2})^2 U[n]$ , yielding output  $y[n]$ .

(a) Determine  $R_{yx}[l]$ .

(b) Determine  $R_y[l]$ .

(c) Determine  $S_y(\omega)$

11. (a) Determine the mean of the exponential density function  $f_x(x) = \alpha e^{-\alpha x} U(x)$ , and expressed the density in terms of the mean parameter  $\mu = E\{x\}$ .

(b) Given independence samples  $x_1, x_2, \dots, x_N$ , determine the ML estimate of  $\mu$ .

(c) Is the estimate unbiased?

(d) Is it consistent?

(e) What is the variance of the estimate? Is it a minimum variance estimate?

12. The joint density function of random variables  $x$  and  $y$  is given by

$$f_{xy}(x, y) \begin{cases} 6x & 0 \leq x \leq 1; 0 \leq y \leq 1 - x \\ 0 & \text{otherwise} \end{cases}$$

(a) Determine and sketch the conditional density function  $f_{y|x}(y|x)$ .

(b) Determine the MAP estimate of  $y$ .

- (c) Determine the MS estimate of  $y$ .
- (d) Determine the MAE estimate of  $y$ .

13. A two-dimensional vector  $\mathbf{x}$  and a random variable  $y$  have the joint density

$$f_{\mathbf{x}y}(\mathbf{x}, y) \begin{cases} (y + 3x_1)x_2 & 0 \leq x_1, x_2, y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Assume that  $\mathbf{x}$  represents the observation.

- (a) Determine the MAP estimate of  $y$ .
- (b) Determine the MS estimate of  $y$ .
- (c) Determine the MAE estimate of  $y$ .

14. A random process  $x[n]$  is generated according to the difference equation

$$x[n] = \rho x[n - 1] + \eta[n]$$

where  $\rho$  is a constant and  $\eta[n]$  is a binary whitenoise sequence taking on values  $-1$  and  $+1$  with equal probabilities.

- (a) Generate and plot  $M = 50$  samples of the random sequence for  $\rho = 0.95, 0.70,$  and  $-0.95$ . What differences do you observe in these three random sequences?
- (b) Repeat the above with  $\eta[n]$  a white noise Gaussian sequence with unit variance.
- (c) Let  $\hat{R}_x[l]$  be the sample autocorrelation. Define the estimated correlation coefficient  $\hat{\rho}$  as

$$\hat{\rho} = \frac{\hat{R}_x[1]}{\hat{R}_x[0]}$$

Compute  $\hat{\rho}$  for each of the Gaussian noise driven sequences and for several sequence lengths. How well does the estimated value compare with the theoretical value?

- (d) Plot the estimated  $\hat{R}_x[l]$  and true  $R_x[l]$  autocorrelation functions for  $0 \leq l \leq 1$  for each of the Gaussian noise driven sequences.
- (e) What happens if  $|\rho| > 1$ ?